

Machine Learning Basics

He He

New York University

September 8, 2021

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Generalization

Optimization

Loss functions

Rule-based approach

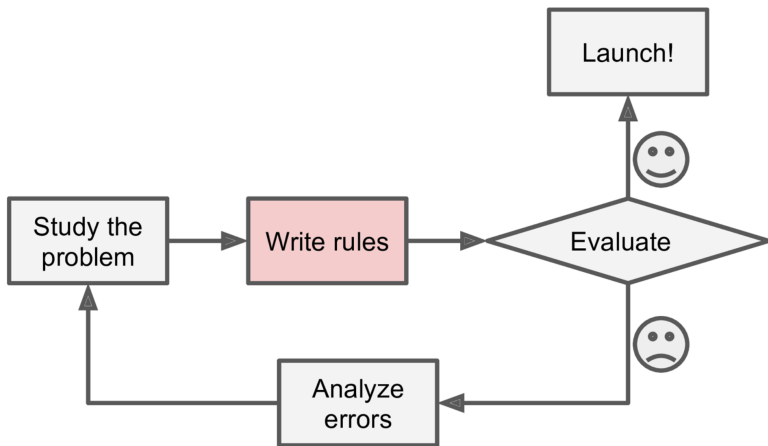


Figure: Fig 1-1 from *Hands-On Machine Learning with Scikit-Learn and TensorFlow* by Aurelien Geron (2017).

Machine learning approach

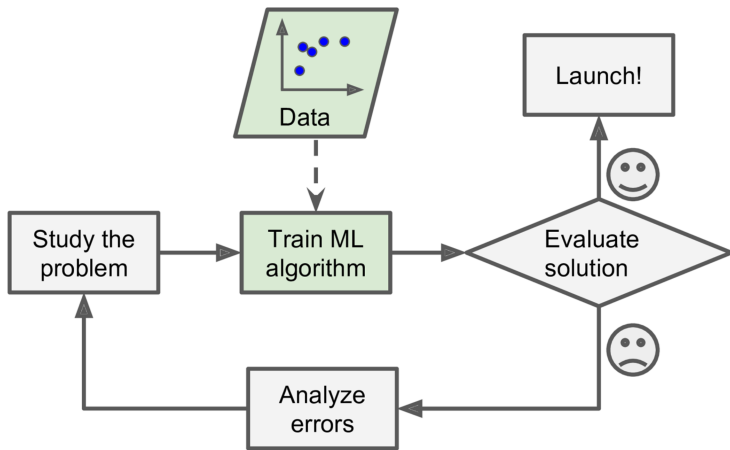


Figure: Fig 1-2 from *Hands-On Machine Learning with Scikit-Learn and TensorFlow* by Aurelien Geron (2017).

Example: spam filter

- ▶ Rules

 - Contains “Viagra”

 - Contains “Rolex”

 - Subject line is all caps

 - ...

- ▶ Learning from data

1. Collect emails labeled as spam or non-spam

2. (Design features)

3. Learn a predictor

Pros and cons?

Keys to success

- ▶ Availability of large amounts of (annotated) data
Scraping, crowdsourcing, expert annotation
- ▶ **Generalize** to unseen samples (test set)
 - ▶ Assume that there is a (unknown) data generating distribution: \mathcal{D} over $\mathcal{X} \times \mathcal{Y}$
 - ▶ Training set: m samples from \mathcal{D} $\{(x^{(i)}, y^{(i)})\}_{i=1}^m$
 - ▶ Learn model $h: \mathcal{X} \rightarrow \mathcal{Y}$
 - ▶ Goal: minimize $\mathbb{E}_{(x,y) \sim \mathcal{D}} [\text{error}(h, x, y)]$ (estimated on the test set)

Empirical risk minimization (ERM)

- ▶ Our goal is to minimize the expected loss (**risk**), but it cannot be computed (why?).
- ▶ How can we estimate it?

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- ▶ Our goal is to minimize the expected loss (**risk**), but it cannot be computed (why?).
- ▶ How can we estimate it?
- ▶ Minimize the average loss (**empirical risk**) on the training set

$$\min_h \frac{1}{m} \sum_{i=1}^m \text{error}(h, x^{(i)}, y^{(i)})$$

- ▶ In the limit of infinite samples, empirical risk converges to risk (LLN).
- ▶ Given limited data though, can we generalize by ERM?

Overfitting vs underfitting

- ▶ Trivial solution to (unconstrained) ERM: **memorize** the data points
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-
- ▶ Constrain the prediction function to a subset, i.e. a **hypothesis space** $h \in \mathcal{H}$.
 - ▶ Trade-off between complexity of \mathcal{H} (approximation error) and estimation error
 - ▶ Question for us: how to choose a good \mathcal{H} for certain domains

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Overall picture

1. Obtain training data $D_{\text{train}} = \{(x^{(i)}, y^{(i)})\}_{i=1}^n$.
2. Choose a loss function L and a hypothesis class \mathcal{H} (domain knowledge).
3. Learn a predictor by minimizing the empirical risk (optimization).

Gradient descent

- ▶ The gradient of a function F at a point w is the direction of fastest increase in the function value
- ▶ To minimize $F(w)$, move in the opposite direction

$$w \leftarrow w - \eta \nabla_w F(w)$$

- ▶ Converge to a local minimum (also global minimum if $F(w)$ is **convex**) with carefully chosen step sizes

Convex optimization (unconstrained)

- ▶ A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is convex if for all $x, y \in \mathbb{R}^d$ and $\theta \in [0, 1]$ we have

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y) .$$

- ▶ f is concave if $-f$ is convex.
- ▶ Locally optimal points are also globally optimal.
- ▶ For unconstrained problems, x is optimal iff $\nabla f(x) = 0$.

Stochastic gradient descent

- ▶ **Gradient descent (GD)** for ERM

$$w \leftarrow w - \eta \nabla_w \underbrace{\sum_{i=1}^n L(x^{(i)}, y^{(i)}, f_w)}_{\text{training loss}}$$

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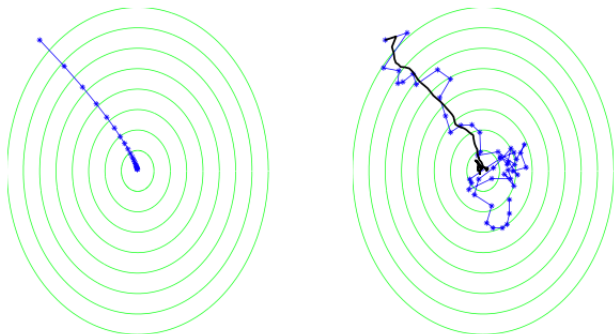
- ▶ **Stochastic gradient descent (SGD)**: take noisy but faster steps

For each $(x, y) \in D_{\text{train}}$:

$$w \leftarrow w - \eta \nabla_w \underbrace{L(x, y, f_w)}_{\text{example loss}}$$

GD vs SGD

Figure: Minimize $1.25(x + 6)^2 + (y - 8)^2$



(Figure from “Understanding Machine Learning: From Theory to Algorithms” .)

Stochastic gradient descent

- ▶ Each update is efficient in both time and space
- ▶ Can be slow to converge
- ▶ Popular in large-scale ML, including non-convex problems
- ▶ In practice,
 - Randomly sample examples.
 - Fixed or diminishing step sizes, e.g. $1/t$, $1/\sqrt{t}$.
 - Stop when objective does not improve.

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Generalization

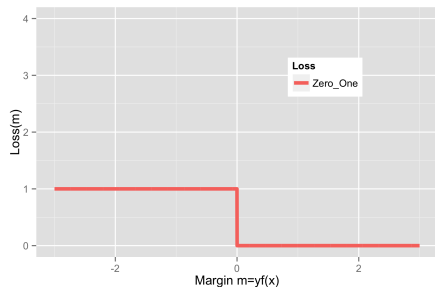
Optimization

Loss functions

Zero-one loss

- ▶ Binary classification: $y \in \{+1, -1\}$.
 - ▶ Model: $f_w: \mathcal{X} \rightarrow \mathbb{R}$ parametrized by $w \in \mathbb{R}^d$.
 - ▶ Output prediction: $\text{sign}(f_w(x))$.
- ▶ Zero-one (0-1) loss

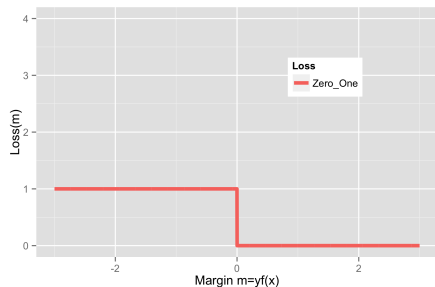
$$L(x, y, f_w) = \mathbb{I}[\text{sign}(f_w(x)) \neq y] = \mathbb{I}[yf_w(x) \leq 0] \quad (1)$$



Zero-one loss

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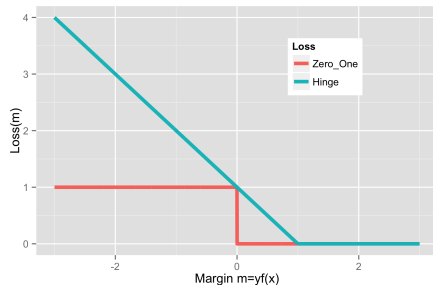
$$L(x, y, f_w) = \mathbb{I}[\text{sign}(f_w(x)) \neq y] = \mathbb{I}[yf_w(x) \leq 0] \quad (1)$$



Not feasible for ERM

Hinge loss

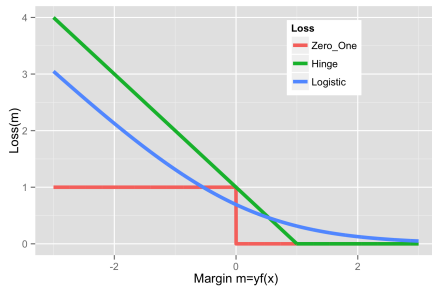
$$L(x, y, f_w) = \max(1 - yf_w(x), 0)$$



- ▶ Loss is zero if margin is larger than 1
- ▶ Not differentiable at margin = 1
- ▶ Subgradient: $\{g: f(x) \geq x_0 + g^T(x - x_0)\}$

Logistic loss

$$L(x, y, f_w) = \log(1 + e^{-yf_w(x)})$$



- ▶ Differentiable
- ▶ Always wants more margin (loss is never 0)

Summary

- ▶ Bias-complexity trade-off: choose hypothesis class based on prior knowledge
- ▶ Learning algorithm: empirical risk minimization
- ▶ Optimization: stochastic gradient descent