Pretraining and Finetuning

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February 19, 2025

Table of Contents

Review

Introduction

Tokenization

Architectures of pretrained models

Optimization

Last week

- Encoders: tokens to vectors
- Decoders: vectors to tokens
- Key difference: (autoregressive) decoders cannot look at the future
 - Need causal masking
 - Sequential output

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Table of Contents

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- Simple features (e.g. unigram BoW) require complex models.
- Good features only need simple models (e.g. linear classifier) .

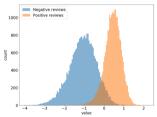


Figure: Sentiment neuron [Radford et al., 2017]

What can we do with good representations:

- Learning with small data: fine-tuning learned representations
- Transfer learning: one model/representation for many tasks
- Metric learning: get a similarity metric

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How to obtain such a representation:

- Training a neural network on any task gives us a representation good for *that task*.
- But on which task can we learn good general representations?

• The cats that are raised by my sister ______ sleeping.

- The cats that are raised by my sister ______ sleeping.
- Jane is happy that John invited ______ friends to his birthday party.

syntax

- The cats that are raised by my sister ______ sleeping. syntax
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- _____ is the capital of Tanzania.

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Text contains a surprisingly large number of tasks!

Self-supervised learning for representation learning

Key idea: predict parts of the input from the rest

- No additional supervision is needed—both input and output are from the raw text data.
- Easy to scale—massive amount of text on the Internet.
- Learned representation is general—useful for any tasks that can be performed in textual mode.

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Approach:

- **Pretrain**: train a model using self-supervised learning objectives on large data.
- **Finetune**: update part or all of the parameters of the pretrained model on labeled data of a downstream task.

- Pretrain an RNN model on unlabeled data and finetune on supervised tasks [Dai et al., 2015] [ULMFiT; Howard et al., 2018]
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- Pretrain a Transformer model and finetune on supervised tasks
 - GPT [Radford et al., 2018], BERT [Devlin et al., 2018]
- Scale pretrained transformer to larger data and compute
 - Can directly answer user questions and solve many tasks, e.g., ChatGPT, Claude, Deepseek-chat

Table of Contents

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Challenges in tokenization

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• A long tail of rare words

Neologism, terminologies, misspelling, informal text, etc.

• A mixture of multiple natural languages, programming languages, special symbols

Low-resource language, math equations, code-switching, emoji, etc.

Efficiency

Trade-off between vocab size and sequence length, latency

Subword tokenization

The most widely adopted solution: decomposing words into subword units

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Efficiency

Balancing granularity and efficiency: reducing token count without losing meaning

Byte pair encoding (BPE)

What is a "token"?

- A sequence of characters that carries some meaning and re-occurs in a corpora
- Can we find these character units based on their frequency?

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BPE:

- Origin: a compression algorithm that iteratively replace the most common character sequences by a single symbol, e.g., $un \rightarrow A$
- Start with individual characters as tokens
- Merge the most frequent pair of tokens and treat them as a single token
- Update the input with the new token and repeat the process
- Output: tokenized text and a set of merge rules

BPE Example (Step-by-Step) Initial Sequence:

- Words: banana, band, ban
- Initial tokenization (by character):
 - banana
 - b a n d
 - b a n

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Step 1: Count Pairs

• What is the most frequent pair:

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Step 2: Merge

- New merge rule: a, $n \rightarrow an$
- Updated tokenization:
 - b a n a n a ightarrow
 - b a n d ightarrow
 - b a n ightarrow

BPE Example (Step-by-Step)

Step 3: Count Pairs Again

- Updated tokenization:
 - b an an a
 - b an d
 - b an
- Most frequent pair: b an

Step 4: Merge

- New merge rule: b, an ightarrow ban
- Updated tokenization:
 - ban an a
 - ban d
 - ban

BPE: practicalities

- Repeat the process until the desired number of merges or vocabulary size is reached (a hyperparameter to decide). Typically vocabulary sizes are 32-64K.
- Break ties deterministically, e.g., lexicographical order, occurrence in the corpus etc.
- Use bytes as the initial tokens (adopted by GPT-2)
- Variants: instead of merging the pair with the largest frequency, **WordPiece** merges the pair that maximizes the log likelihood of the training data, i.e. Merge a, b if

$$\log p(a, b) - \log p(a)p(b)$$

is the largest among all pairs

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Current pretrained models are all transformer based.

Encoder models

An encoder takes a sequence of tokens and output their *contextualized* representations:

$$h_1,\ldots,h_n = \operatorname{Encoder}(x_1,\ldots,x_n)$$

We can then use h_1, \ldots, h_n for other tasks.

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How do we train an $\operatorname{Encoder}\nolimits?$

- Use any supervised task: $y = f(h_1, \ldots, h_n)$
- Use self-supervised learning: predict a word from its context

Masked language modeling

? language processing is ?

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Learning objective (MLE):

$$\max \sum_{x \in \mathcal{D}, i \sim p_{\mathsf{mask}}} \log p(x_i \mid x_{-i}; \theta)$$

- *x*: a sequence of tokens sampled from a corpus *D natural language processing is fun*
- *p*_{mask}: mask generator
 Sample two positions uniformly at random, e.g., 1 and 5
- x_{-i}: noisy version fo x where x_i is corrupted [MASK] language processing is [MASK]

BERT: objective

Masked language modeling:

- Randomly sample 15% tokens as prediction targets
- Replace the target tokens by [MASK] or a random token, or leave it unchanged

cats are cute \rightarrow cats [MASK]/is/are cute

• Later work has shown that just use [MASK] is sufficient

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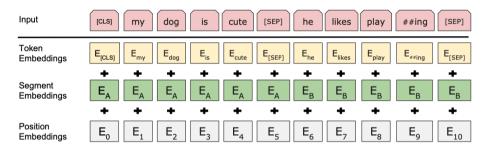
- Later work has shown that just use [MASK] is sufficient
- Next sentence prediction: predict whether a pair of sentences are consecutive

$$\max \sum_{x \sim \mathcal{D}, x_n \sim p_{\mathsf{next}}} \log p(y \mid x, x_n; \theta)$$

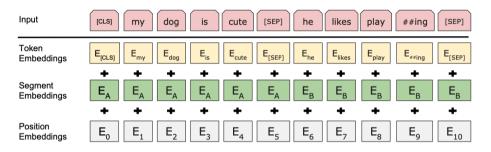
- x_n : either the sentence following x or a randomly sampled sentence
- *y*: binary label of whether x_n follows *x*
- Later work has shown that this objective is not necessary

Input	[CLS] my dog is cute [SEP] he likes play ##ing [SEP]
Token Embeddings	$\label{eq:cls} \left[\begin{array}{c} E_{my} \end{array} \right] \left[\begin{array}{c} E_{dog} \end{array} \right] \left[\begin{array}{c} E_{is} \end{array} \right] \left[\begin{array}{c} E_{cute} \end{array} \right] \left[\begin{array}{c} E_{lee} \end{array} \right] \left[\begin{array}{c} E_{he} \end{array} \right] \left[\begin{array}{c} E_{play} \end{array} \right] \left[\begin{array}{c} E_{s*ing} \end{array} \right] \left[\begin{array}{c} E_{ISEP} \end{array} \right] \left[\begin{array}{c} E_{nikes} \end{array} \right] \left[\begin{array}{c} E_{play} \end{array} \right] \left[\begin{array}{c} E_{s*ing} \end{array} \right] \left[\begin{array}{c} E_{ISEP} \end{array} \right] \left[\begin{array}{c} E_{nikes} \end{array} \right] \left[\begin{array}{c} E_{play} \end{array} \right] \left[\begin{array}{c} E_{s*ing} \end{array} \right] \left[\begin{array}{c} E_{ISEP} \end{array} \right] \left[\begin{array}{c} E_{nikes} \end{array} \right] \left[\begin{array}{c} E_{ning} \end{array} \right] \left[\begin{array}[\\ E_{ning} \end{array} \right] \left[\begin{array}[\\ E_{ning} \end{array} \right] \left[\begin{array}[\\ E_{ning} \end{array} \right] \left[\left[\\ E_{ning} \end{array} \right] \left[\left[\\ E_{ning} \end{array} \right] \left[\left[\left[E_{ning} \end{array} \right] \left[\left[\left[E_{ning} \end{array} \right] \right] \left[\left[\left[E_{ning} \end{array} \right] \left[\left[$
Segment Embeddings	$\begin{array}{c} \bullet \\ \bullet $
Position Embeddings	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

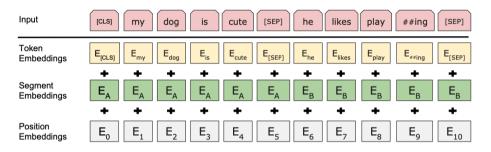
• Tokenization: wordpiece (similar to byte pair encoding) (see details)



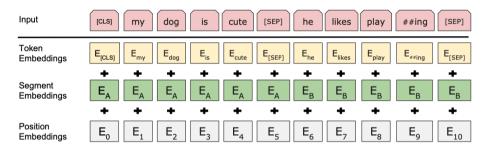
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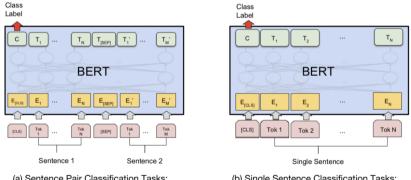


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- [CLS]: first token of all sequences; used for next sentence prediction
- Distinguish two sentences in a pair: [SEP] and segment embedding
- Learned position embedding
- 12 (base; 110M params) or 24 (large; 340M params) layer Transformer

Finetuning BERT

Classification tasks: Add a linear layer (randomly initialized) on top of the [CLS] embedding

$$p(y \mid x) = \operatorname{softmax}(Wh_{[CLS]} + b)$$



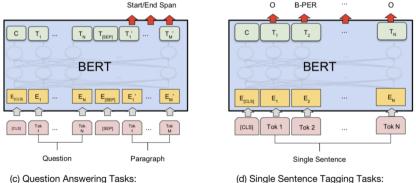
(a) Sentence Pair Classification Tasks: MNLI, QQP, QNLI, STS-B, MRPC, RTE, SWAG (b) Single Sentence Classification Tasks: SST-2, CoLA

Finetuning BERT

SQuAD v1.1

Sequence labeling tasks: Add linear layers (randomly initialized) on top of every token

$$p(y_i \mid x) = \operatorname{softmax}(Wh_i + b)$$



(d) Single Sentence Tagging Tasks: CoNLL-2003 NER

Finetuning BERT

- Finetune all parameters (both the newly added layer and the pretrained weights)
- Use a small learning rate (e.g., 1e-5)
- Train for a small number of epochs (e.g, 3 epochs)
- Led to SOTA results on many NLU tasks



How to generate text from BERT?

Encoder-decoder models

An encoder-decoder model encodes input text to a sequence of contextualized representations, and decodes a sequence of tokens autoregressively.

$$\begin{aligned} h_1, \dots, h_n &= \operatorname{Encoder}(x_1, \dots, x_n) \\ s_1, \dots, s_m &= \operatorname{Decoder}(y_0, \dots, y_{m-1}, h_1, \dots, h_n) \\ p(y_i \mid x, y_{< i}) &= \operatorname{softmax}(Ws_i + b) \end{aligned}$$

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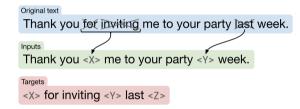
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How do we train the encoder-decoder?

- Use any supervised task, e.g., machine translation
- Use self-supervised learning: predict text spans from their context

Masked language modeling using an encoder-decoder

Input: text with corrupted spans **Output**: recovered spans

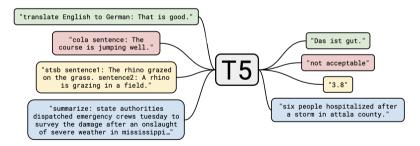


Compare with encoder-only models:

- Encoder: predict single tokens based on encoder representation
- Encoder-decoder: predict a sequence of tokens (flexibility in objective design)

T5: objective

- First train on unlabele data by masked language modeling
 - Predict corrupted spans as a sequence
- Then continue training by supervised multitask learning
 - Formulate tasks as text-to-text format using a prefix to denote the task
 - Mixing examples from different datasets when constructing batches



Jointly training with the two objectives works slightly worse

T5: finetune

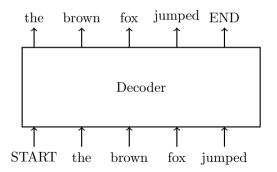
- Formulate the task in text-to-text format
- Fine-tune all parameters (similar to BERT fine-tuning)
- Advantages over encoder models: unified modeling of many different tasks including text generation

Decoder-only models

A decoder-only model predicts the next token given the prefix autoregressively.

$$\begin{aligned} s_1, \dots, s_m &= \text{Decoder}(y_0, \dots, y_{m-1}, h_1, \dots, h_n) \\ \rho(y_i \mid y_{< i}) &= \text{softmax}(Ws_i + b) \end{aligned}$$

(A prefix of *y* can be the input.)



(more on language models later)

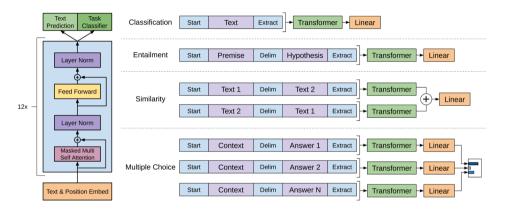
Generative Pretraining (GPT)

- Model: 12 layer decoder-only transformer
- Objective: next word prediction

$$\max \sum_{y \in \mathcal{D}} \sum_{i} \log p(y_i \mid y_{< i})$$

• **Finetuning**: auxiliary LM objective $L_{task} + \lambda L_{LM}$ (next word prediction on labeled task data)

Generative Pretraining (GPT): task-specific finetuning



- Single input: linear on top of extract
- Multiple input: process each input separately then aggregate

Ablation studies of GPT

Architecture, pretraining, finetuning: which is critical?

Method	Avg. Score	CoLA (mc)	SST2 (acc)	MRPC (F1)	STSB (pc)	QQP (F1)	MNLI (acc)	QNLI (acc)	RTE (acc)
Transformer w/ aux LM (full)	74.7	45.4	91.3	82.3	82.0	70.3	81.8	88.1	56.0
Transformer w/o pre-training Transformer w/o aux LM LSTM w/ aux LM	59.9 75.0 69.1	18.9 47.9 30.3	84.0 92.0 90.5	79.4 84.9 83.2	30.9 83.2 71.8	65.5 69.8 68.1	75.7 81.1 73.7	71.2 86.9 81.1	53.8 54.4 54.6

- Auxiliary objective only helps on larger datasets (MNLI, QQP)
- Pretrained transformer > pretrained LSTM (single layer) > non-pretrained transformer

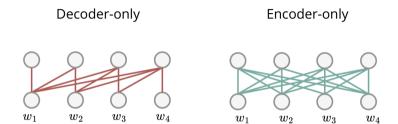
Compare with BERT

System	MNLI-(m/mm)	QQP	QNLI	SST-2	CoLA	STS-B	MRPC	RTE	Average
	392k	363k	108k	67k	8.5k	5.7k	3.5k	2.5k	-
Pre-OpenAI SOTA	80.6/80.1	66.1	82.3	93.2	35.0	81.0	86.0	61.7	74.0
BiLSTM+ELMo+Attn	76.4/76.1	64.8	79.8	90.4	36.0	73.3	84.9	56.8	71.0
OpenAI GPT	82.1/81.4	70.3	87.4	91.3	45.4	80.0	82.3	56.0	75.1
BERTBASE	84.6/83.4	71.2	90.5	93.5	52.1	85.8	88.9	66.4	79.6
BERTLARGE	86.7/85.9	72.1	92.7	94.9	60.5	86.5	89.3	70.1	82.1

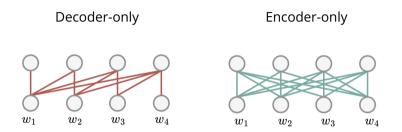
Table 1: GLUE Test results, scored by the evaluation server (https://gluebenchmark.com/leaderboard). The number below each task denotes the number of training examples. The "Average" column is slightly different than the official GLUE score, since we exclude the problematic WNLI set.⁸ BERT and OpenAI GPT are single-model, single task. F1 scores are reported for QQP and MRPC, Spearman correlations are reported for STS-B, and accuracy scores are reported for the other tasks. We exclude entries that use BERT as one of their components.

Medium-sized encoder models tend to work better than decoder-only models when finetuned

Encoder-only vs decoder-only models: attention



Encoder-only vs decoder-only models: attention



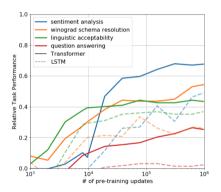
Encoder-only models provides better embeddings due to bidirectional attention.

Encoder-only vs decoder-only models: generation

Decoder-only models can make predictions through generation without finetuning

Encoder-only vs decoder-only models: generation

Decoder-only models can make predictions through generation without finetuning



Heuristics for zero-shot prediction:

- Sentiment classification: [example] + very + {positive, negative} prompting
- Linguistic acceptability: thresholding on log probabilities
- Multiple choice: predicting the answer with the highest log probabilities

Scaling trend: zero-shot performance increases during pretraining

Encoder-only vs decoder-only models: training efficiency

On each sequence:

- Encoder-only models are trained on 15% (mask rate) of the tokens
- Decoder-only models are trained on all tokens

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What about encoder-decoder models?

- Flexibility on encoder design, e.g., full attention on input context
- Limited advantage on long-form generation tasks over decoder-only model
- More resource available for decoder-only models

Table of Contents

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What are challenges of optimization in pretraining?

- Numerical stability (no NaN and diverging losses) initialization, normalization, learning rate schedule
- Memory efficiency (work with billions of parameters) mixed precision, gradient accumulation

Key ideas:

- Momentum
 - Motivation: having an inertia of moving in the same direction \rightarrow reduce oscillation
 - How: maintain a "memory" (moving average) of past updates

Key ideas:

- Momentum
 - Motivation: having an inertia of moving in the same direction \rightarrow reduce oscillation
 - How: maintain a "memory" (moving average) of past updates
- Adaptive step size for each parameter
 - Intuition:

flat regions (gradient changing slowly) \rightarrow take larger steps steep regions (gradient changing fast) \rightarrow take smaller steps

• Handle sparse features well (e.g., rare words embeddings aren't updated often)

• Compute gradient g_t

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- Update first order moments (mean)

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(2)

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Correct bias in moment estimates

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• Update parameters

$$\theta_t = \theta_{t-1} - \eta \frac{\hat{m}_t}{\sqrt{\hat{v}_t} + \epsilon} \tag{4}$$

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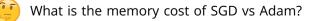
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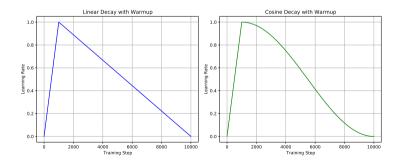
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Learning rate schedule

- Warmup: don't want to start with large learning rate for stability
- **Decay**: reducing learning rate as model converges linear (used by BERT), cosine, exponential



Gradient accumulation

Simulate large batch training with limited GPU memory

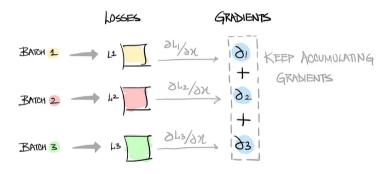


Figure: From Harshit Sharma