

Neural Sequence Modeling

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NEW YORK UNIVERSITY

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Introduction

Multilayer perceptron

Recurrent neural networks

Self-attention

Transformer

Last Week

- What is the core principle underlying learning word vectors?

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- **Count-based word embedding**: using SVD to discover latent features
- **Prediction-based word embedding**: directly learning word vectors to optimize "correlation" between a word and its context
 - Use **negative sampling** to speed up training

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Multilayer perceptron

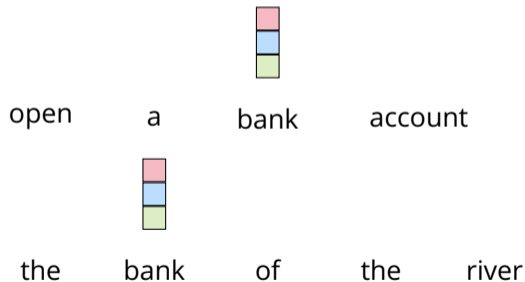
Recurrent neural networks

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Limitation of word embeddings

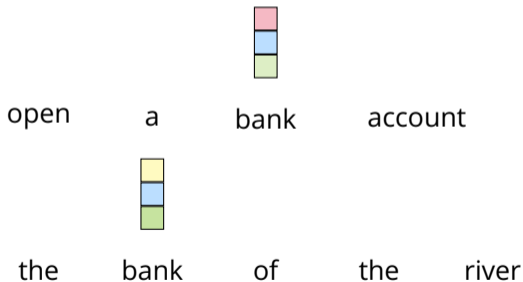
So far we have assumed tokens are (conditionally) independent to each other, and they have **deterministic** representations



Limitation of word embeddings

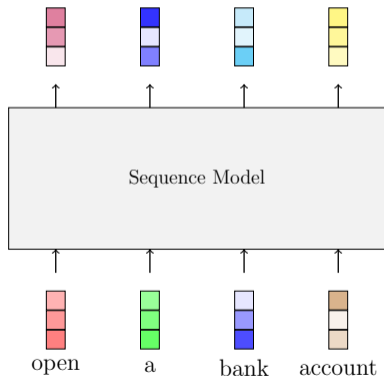
So far we have assumed tokens are (conditionally) independent to each other, and they have **deterministic** representations

Ideally we want the representation to **depend on context**



Modeling a sequence of tokens

Problem setup: given an input sequence of tokens (or their embeddings), outputs **contextualized** embeddings for each token, which can then be used for downstream tasks.



Modeling a sequence of tokens

Key challenge: how to model interaction among words?

Modeling a sequence of tokens

Key challenge: how to model interaction among words?

Approach:

- Dense interaction
- Recurrence
- Self-attention

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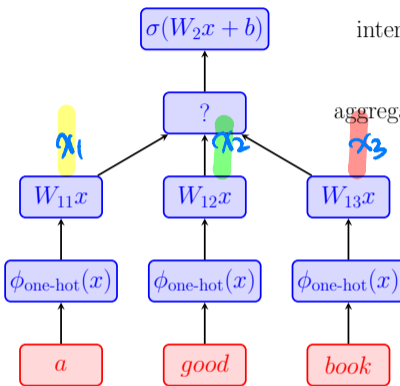
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Feed-forward neural network for sequence modeling



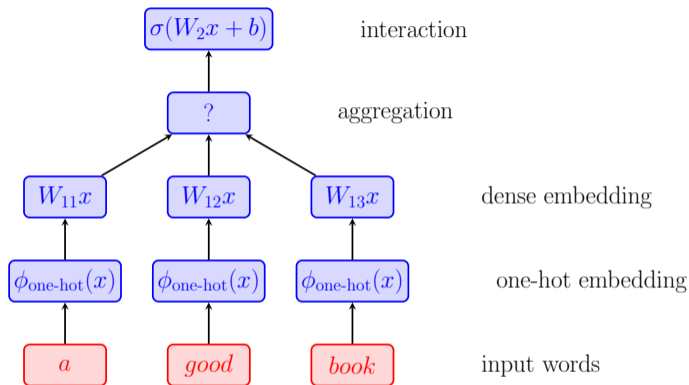
interaction $\sigma(W_2(x_1 + x_2 + x_3) + b)$
 $P \times P$ $P > 1$

dense embedding

one-hot embedding

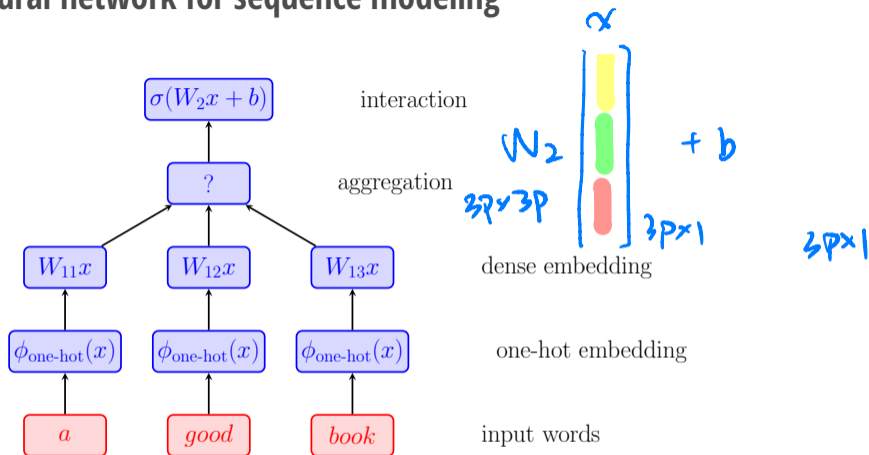
input words

Feed-forward neural network for sequence modeling



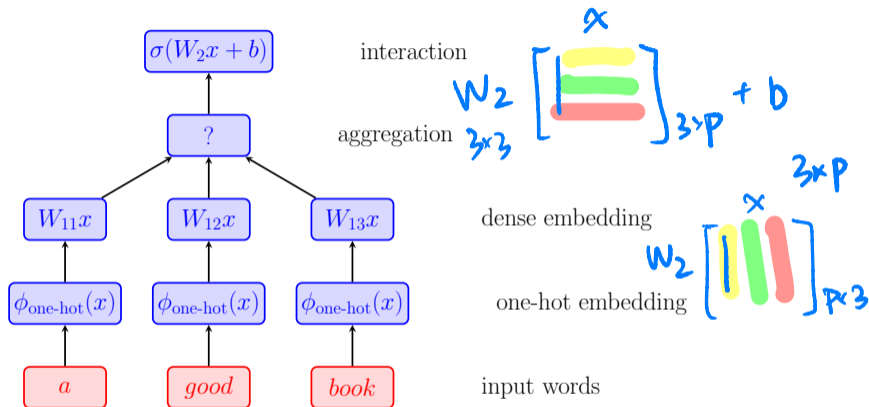
How to aggregate input word embeddings so that they can be interacted through a linear layer?

Feed-forward neural network for sequence modeling



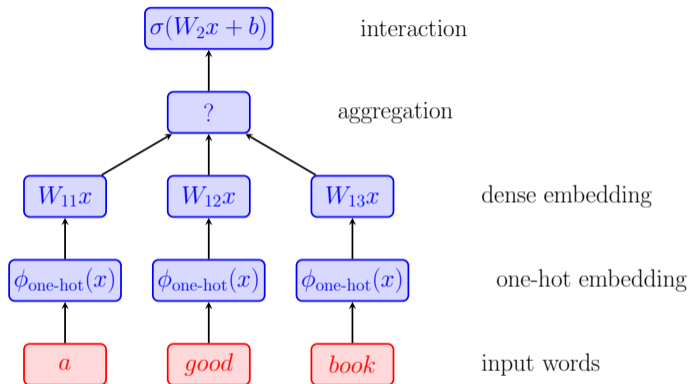
1. Concatenate along the feature dimension: $1 \times p \rightarrow 3p \times 1$

Feed-forward neural network for sequence modeling



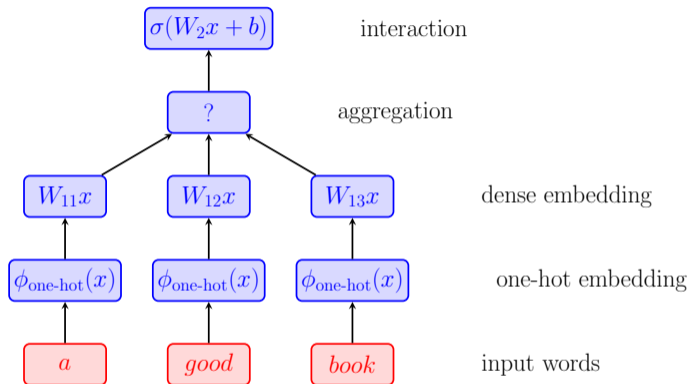
2. Concatenate along the token dimension: $1 \times p \rightarrow 3 \times p$

Feed-forward neural network for sequence modeling



3. Concatenate along the token dimension then transpose: $1 \times p \rightarrow p \times 3$

Feed-forward neural network for sequence modeling



Can it model sequences of arbitrary lengths?

Summary

- Different concatenation interacts different aspects of the input
 - Mixing all features in all tokens
 - Mixing a specific feature in all tokens
 - Mixing all features in a specific token
- Can use different mixing strategies in different MLP layers
- Design considerations: efficiency vs expressivity
- See more at [MLP-Mixer: An all-MLP Architecture for Vision](#)

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Recurrent neural networks

- **Idea:** combine new tokens with previous tokens [recurrently](#)

Recurrent neural networks

- **Idea:** combine new tokens with previous tokens **recurrently**
 - Update the representation, i.e. **hidden states** h_t , recurrently

$$h_t = f(h_{t-1}, x_t)$$

- Output from previous time step is the input to the current time step
- Apply the same transformation f at each time step

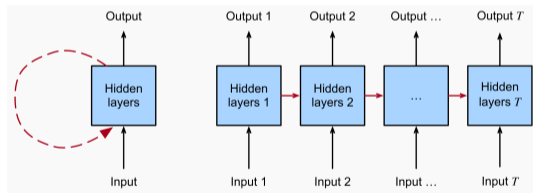
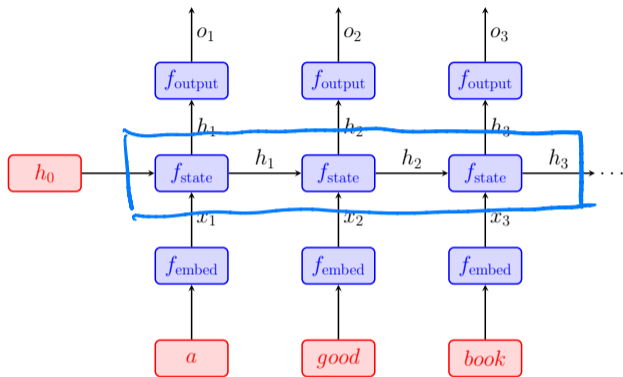


Figure: 9.1 from d2l.ai

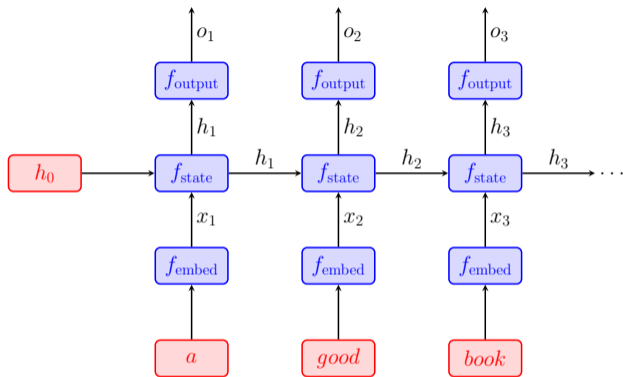
- Output the hidden states: the representation of the t -th token incorporates its left context

Forward pass



A deep neural network with shared weights in each layer

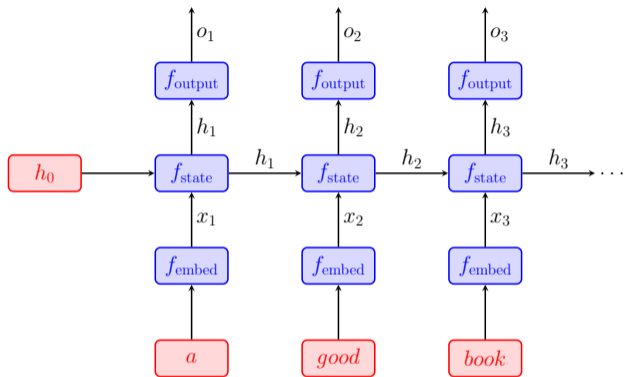
Forward pass



$$\begin{aligned}x_t &= f_{\text{embed}}(s_t) \\ &= W_e \phi_{\text{one-hot}}(s_t)\end{aligned}$$

A deep neural network with shared weights in each layer

Forward pass

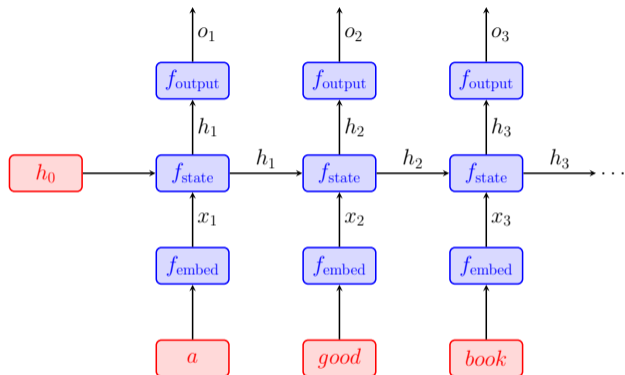


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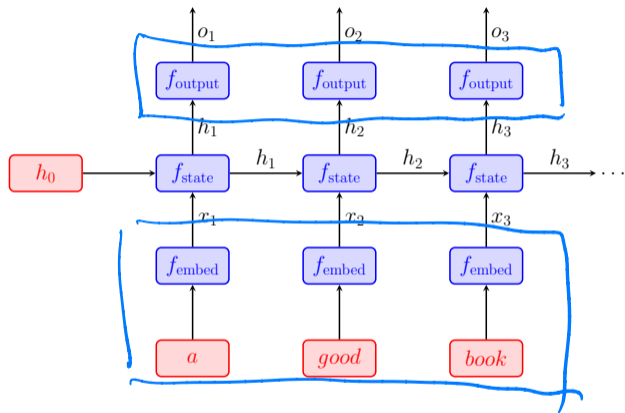
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(a distribution over classes)

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Which computation can be parallelized?

Using RNNs in downstream tasks

Sequence labeling and language modeling:

- Input: x_1, \dots, x_T (a sequence of tokens)
- Output: y_1, \dots, y_T (e.g., POS tags, next words)
- Loss function: $\sum_{i=1}^T \ell(y_t, o_t)$
 - NLL loss: $\sum_{i=1}^T -\log o_t[y_t]$

Using RNNs in downstream tasks

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 - NLL loss: $\sum_{i=1}^T -\log o_t[y_t]$

Text classification:

- Input: x_1, \dots, x_T
- Output: $y \in \{1, \dots, K\}$ (K classes)
- Loss function: $\ell(y, f_{\text{output}}(\text{pool}(h_1, \dots, h_T)))$
 - Can use last hidden state or mean of all hidden states

Backward pass

Given the loss $\ell(y_t, o_t)$, compute the gradient with respect to W_{hh} .

$$\frac{\partial \ell_t}{\partial W_{hh}} = \frac{\partial \ell_t}{\partial o_t} \frac{\partial o_t}{\partial h_t} \frac{\partial h_t}{\partial W_{hh}}$$

Backward pass

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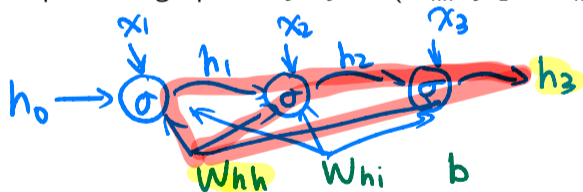
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Computation graph of h_t : $h_t = \sigma(W_{hh}h_{t-1} + W_{hi}x_t + b)$



$$\frac{\partial h_3}{\partial W_{hh}} = \frac{\partial h_3^+}{\partial W_{hh}} + \frac{\partial h_3}{\partial h_2} \cdot \frac{\partial h_2}{\partial W_{hh}} + \frac{\partial h_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial W_{hh}}$$

Backpropagation through time

Problem with standard backpropagation:

- Gradient involves **repeated multiplication of W_{hh}**
- Gradient will **vanish / explode** (depending on the eigenvalues of W_{hh})

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- Gradient involves **repeated multiplication of W_{hh}**
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Quick fixes:

- **Truncated BPTT**: reduce the number of repeated multiplication by truncating after k steps (h_{t-k} has no influence on h_t)
- **gradient clipping**: limit the norm (or value) of the gradient in each step; can only mitigate explosion

Long-short term memory (LSTM)

Vanilla RNN: always update the hidden state

- Cannot handle long range dependency due to gradient vanishing

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LSTM: learn when to update the hidden state

- First successful solution to the gradient vanishing and explosion problem

Long-short term memory (LSTM)

Vanilla RNN: always update the hidden state

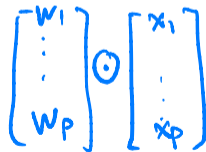
- Cannot handle long range dependency due to gradient vanishing

LSTM: learn when to update the hidden state

- First successful solution to the gradient vanishing and explosion problem

Key idea is to use a **gating mechanism**: multiplicative weights that modulate another variable

- How much should the new input affect the state?
- How much should the state affect the output?



A hand-drawn diagram in blue ink illustrating a gating mechanism. It shows two vertical vectors enclosed in square brackets. The left vector has elements w_1 , a vertical ellipsis, and w_p . The right vector has elements x_1 , a vertical ellipsis, and x_p . A small circle with a dot inside is positioned between the two vectors, representing an element-wise multiplication operation.

Long-short term memory (LSTM) cell

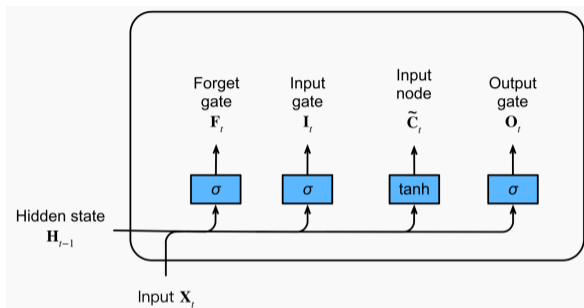


Figure: 10.1.2 from d2l.ai

Cell input: current state, new input

Cell output: updated state

Long-short term memory (LSTM) parametrization

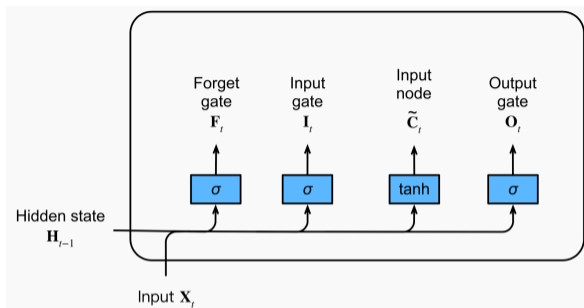


Figure: 10.1.2 from d2l.ai

Tentatively update with the new input x_t (same as in vanilla RNN)

$$\tilde{c}_t = \tanh(W_{xc}x_t + W_{hc}h_{t-1} + b_c) \quad \text{new cell content}$$

But don't commit to h_t yet.

Long-short term memory (LSTM) parametrization

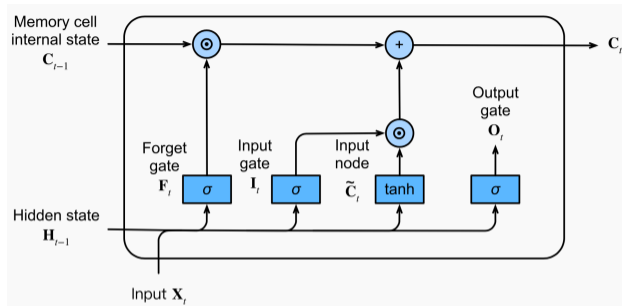


Figure: 10.1.3 from d2l.ai

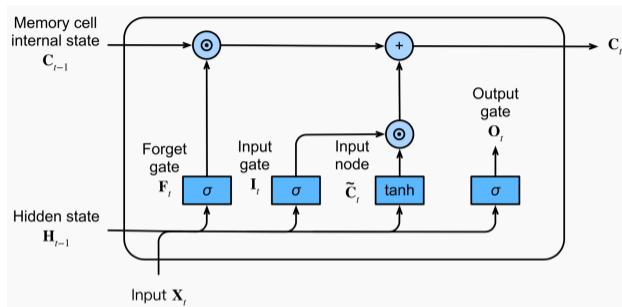
Choose between \tilde{c}_t (update) and c_{t-1} (no update): (\odot : elementwise product)

memory cell
$$c_t = i_t \odot \tilde{c}_t + f_t \odot c_{t-1}$$

$[0, 1]$

- f_t : proportion of the old state (preserve \uparrow or erase \downarrow the old memory)
- i_t : proportion of the new state (write \uparrow or ignore \downarrow the new input)
- What is c_t if $f_t = 1$ and $i_t = 0$?

Long-short term memory (LSTM) parametrization



Input gate and forget gate **depends on data**:

$$i_t = \text{sigmoid}(W_{xi}x_t + W_{hi}h_{t-1} + b_i) ,$$
$$f_t = \text{sigmoid}(W_{xf}x_t + W_{hf}h_{t-1} + b_f) .$$

Each coordinate is between 0 and 1.

Long-short term memory (LSTM) parametrization

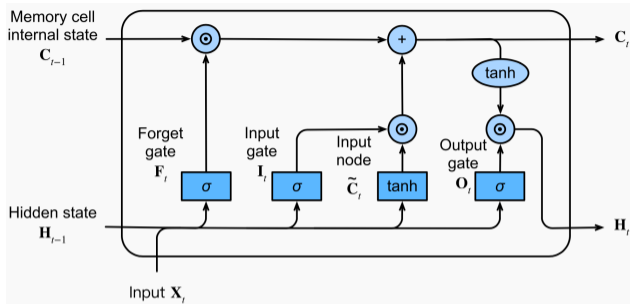


Figure: 10.1.4 from d2l.ai

How much should the memory cell state influence the rest of the network:

$$h_t = o_t \odot c_t$$

$$o_t = \text{sigmoid}(W_{xo}x_t + W_{ho}h_{t-1} + b_o)$$

c_t may accumulate information without impact the network if o_t is close to 0

How does LSTM mitigate gradient vanishing / explosion?

Intuition: gating allows the network to learn to control how much gradient should vanish.

- Vanilla RNN: gradient depends on repeated multiplication of the **same weight matrix**
- LSTM: gradient depends on repeated multiplication of some quantity that depends on the data (values of **input and forget gates**)
- So the network can learn to reset or update the gradient depending on whether there is long-range dependencies in the data.
- Gradient exploding can still happen if dependency is long!

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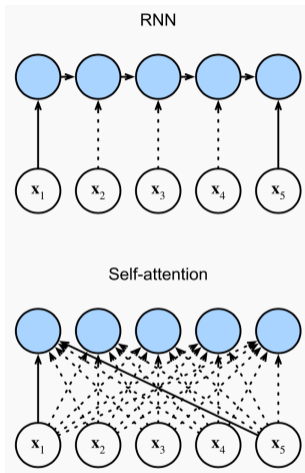
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Improve the efficiency of RNN



Recall that our goal is to come up with a good representation of a sequence of words.

RNN:

- Past words influence the sentence representation through **recurrent update**
- **Sequential computation** $O(\text{sequence length})$, hard to scale

Figure: 11.6.1 from d2l.ai

Improve the efficiency of RNN

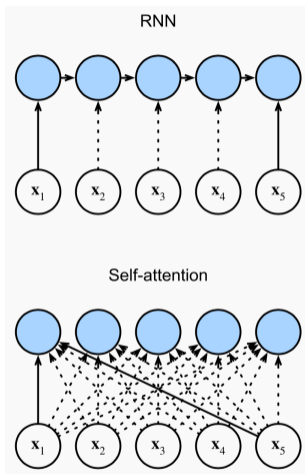


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RNN:

- Past words influence the sentence representation through **recurrent update**
- **Sequential computation** $O(\text{sequence length})$, hard to scale

Can we handle dependency more **efficiently**?

- Interact pairs of tokens in the sequence
- **Parallel computation**

Motivating example

adapted from 3blue1brown

How do we figure out the meaning of "bank"?

open

a

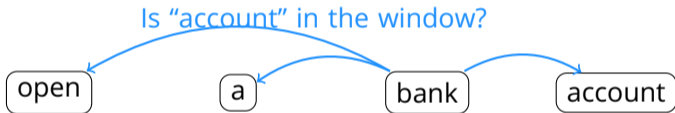
bank

account

Motivating example

adapted from 3blue1brown

How do we figure out the meaning of "bank"?

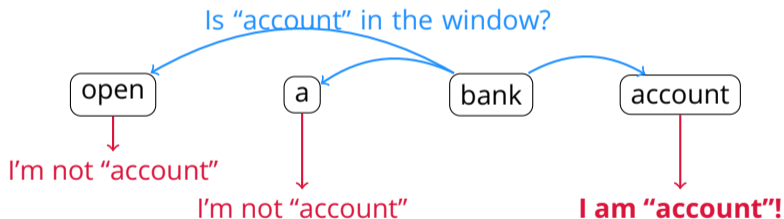


"bank" broadcasts a query

Motivating example

adapted from 3blue1brown

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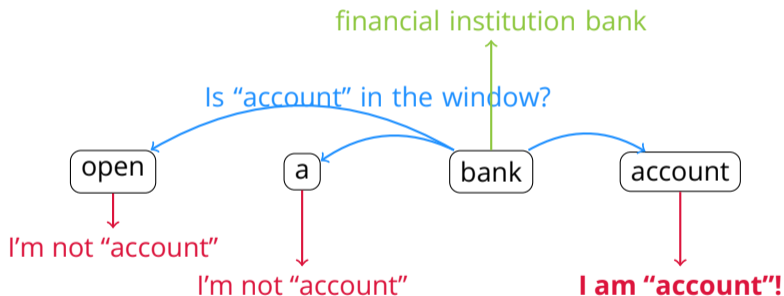


Every word sends a **key** corresponding to the query

Motivating example

adapted from 3blue1brown

How do we figure out the meaning of "bank"?



The **representation** of "bank" is updated by words with **matched keys**

Model interaction between words

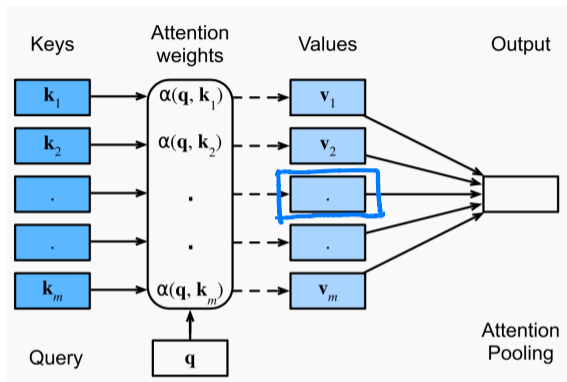


Figure: 11.1.1 from d2l.ai

- **Attention weights** $\alpha(q, k_i)$: how strong is q matched to k_i
- **Attention pooling**: combine v_i 's according to their "relatedness" to the query
- Each word adds its "value" to the target word to modify its meaning

Model interaction between words

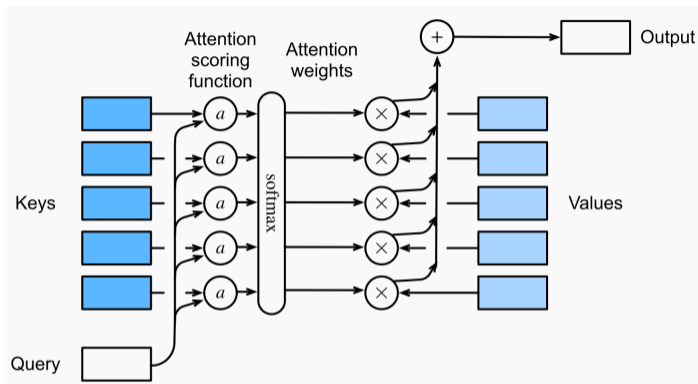
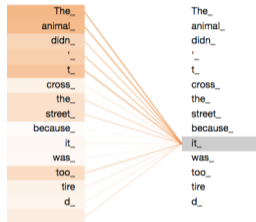
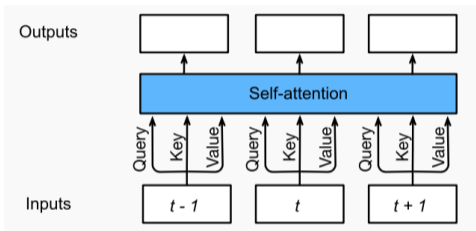


Figure: 11.3.1 from d2l.ai

- Model attention weights as a distribution: $\alpha = \text{softmax}(a(q, k_1), \dots, a(q, k_m))$
- Output a weighted combination of values: $o_i = \sum_{i=1}^m \alpha(q, k_i) v_i$

Self-attention

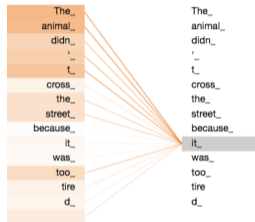
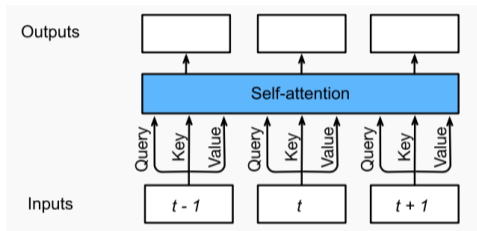
Where do the key, query, and value come from?



- **Input:** map each symbol to a query, a key, and a value (embeddings)

Self-attention

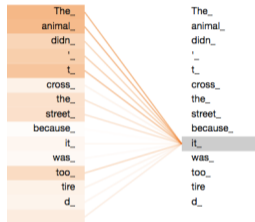
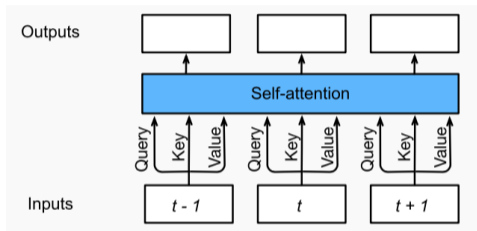
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Self-attention

Where do the key, query, and value come from?



- **Input:** map each symbol to a query, a key, and a value (embeddings)
- **Attend:** each word (as a query) interacts with all words (keys)
- **Output:** *contextualized* representation of each word (weighted sum of values)

Attention scoring functions

Design the function that measures relatedness between queries and keys:

$$\alpha = \text{softmax}(a(q, k_1), \dots, a(q, k_m)) \quad a: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$$

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Dot-product attention

$$a(q, k) = q \cdot k$$

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Dot-product attention

$$a(q, k) = q \cdot k$$

Scaled dot-product attention

$$a(q, k) = q \cdot k / \sqrt{d}$$

- \sqrt{d} : dimension of the key vector
- Avoids large attention weights that push the softmax function into regions of small gradients

Attention scoring functions

Design the function that measures relatedness between queries and keys:

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MLP attention

$$a(q, k) = u^T \tanh(W[q; k])$$

Multi-head attention: motivation

Time flies like an arrow

- Each word attends to all other words in the sentence
- Which words should “like” attend to?

Multi-head attention: motivation

Time flies like an arrow

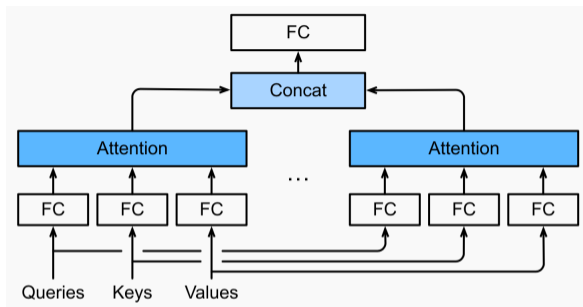
- Each word attends to all other words in the sentence
- Which words should “like” attend to?
 - Syntax: “flies”, “arrow” (a preposition)
 - Semantics: “time”, “arrow” (a metaphor)

Multi-head attention: motivation

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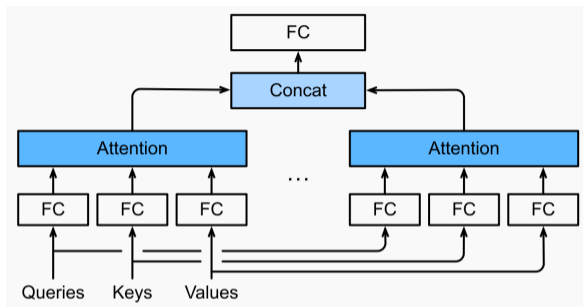
- Each word attends to all other words in the sentence
- Which words should “like” attend to?
 - Syntax: “flies”, “arrow” (a preposition)
 - Semantics: “time”, “arrow” (a metaphor)
- We want to represent different roles of a word in the sentence: need more than a single embedding
- Instantiation: multiple self-attention modules

Multi-head attention



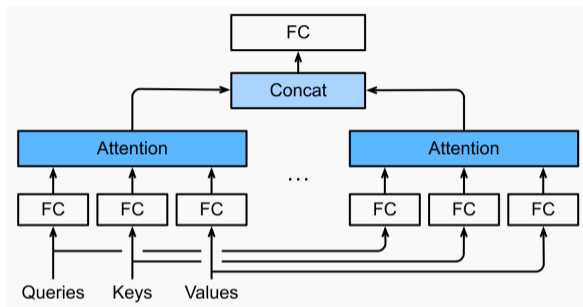
- Multiple attention modules: same architecture, different parameters

Multi-head attention



- Multiple attention modules: same architecture, different parameters
- A **head**: one set of attention outputs

Multi-head attention



- Multiple attention modules: same architecture, different parameters
- A **head**: one set of attention outputs
- Concatenate all heads (increased output dimension)
- Linear projection to produce the final output

Matrix representation: input mapping

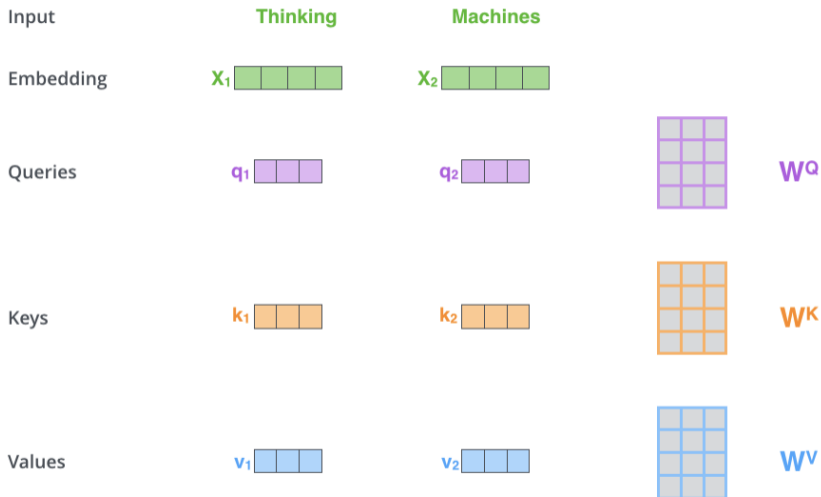
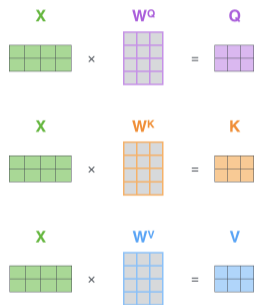


Figure: From [The Illustrated Transformer](#)

Matrix representation: attention weights

Scaled dot product attention



$$\text{softmax}\left(\frac{Q \times K^T}{\sqrt{d_k}}\right) V$$

= Z (pink 2x3 grid)

Figure: From [The Illustrated Transformer](#)

Multi-head attention

1) This is our input sentence*

Thinking
Machines

2) We embed each word*



3) Split into 8 heads. We multiply X or R with weight matrices



4) Calculate attention using the resulting $Q/K/V$ matrices



5) Concatenate the resulting Z matrices, then multiply with weight matrix W^O to produce the output of the layer



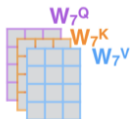
* In all encoders other than #0, we don't need embedding. We start directly with the output of the encoder right below this one



...

...

...



W^O



Z



Figure: From [The Illustrated Transformer](#)

Summary so far

- Sequence modeling
 - Input: a sequence of words
 - Output: a sequence of contextualized embeddings for each word
 - Models interaction among words

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 - Feed-forward / fully-connected neural network
 - Recurrent neural network
 - Self-attention

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Which of these can handle sequences of arbitrary length?

Table of Contents

Review

Introduction

Multilayer perceptron

Recurrent neural networks

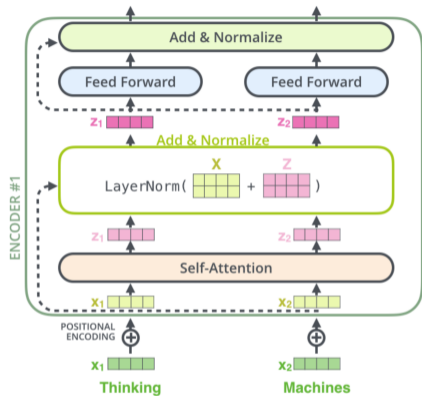
Self-attention

Transformer

Overview

- Use [self-attention](#) as the core building block
- Vastly increased scalability (model and data size) compared to recurrence-based models
- Initially designed for machine translation (next week)
 - *Attention is all you need.* Vaswani et al., 2017.
- The backbone of today's large-scale models
- Extended to non-sequential data (e.g., images and molecules)

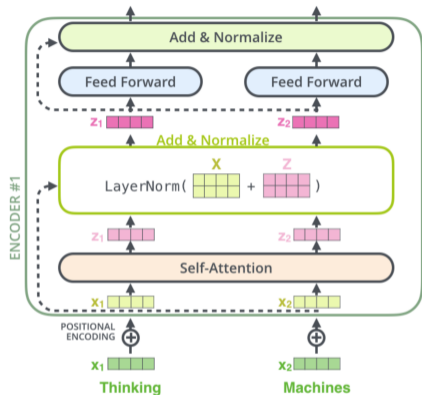
Transformer block



- Multi-head self-attention

Figure: From [The Illustrated Transformer](#)

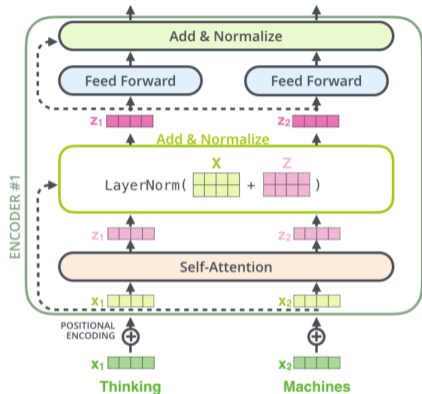
Transformer block



- Multi-head self-attention
 - Capture dependence among input symbols

Figure: From [The Illustrated Transformer](#)

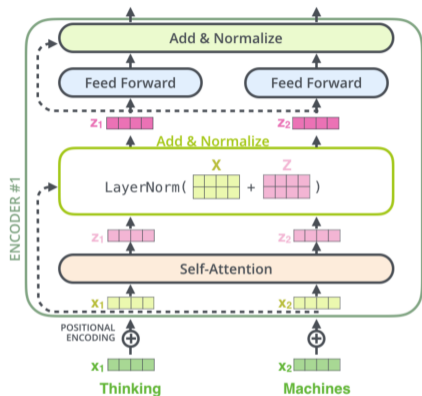
Transformer block



- Multi-head self-attention
 - Capture dependence among input symbols
- Positional encoding

Figure: From [The Illustrated Transformer](#)

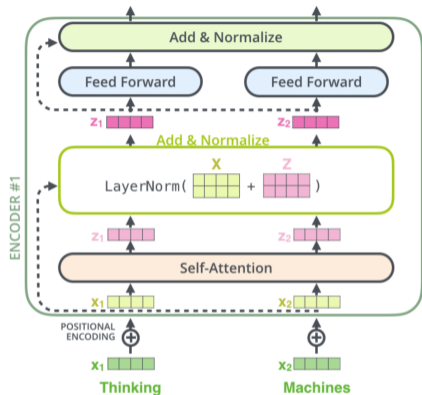
Transformer block



- Multi-head self-attention
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Figure: From [The Illustrated Transformer](#)

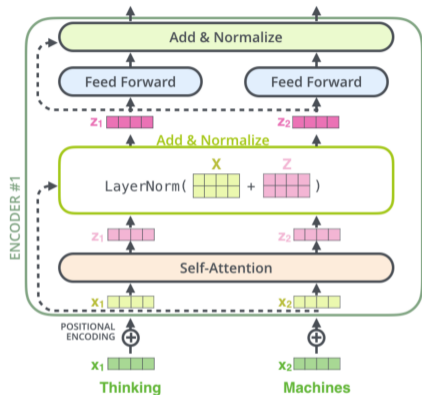
Transformer block



- Multi-head self-attention
 - Capture dependence among input symbols
- Positional encoding
 - Capture the order of symbols
- Residual connection and layer normalization

Figure: From [The Illustrated Transformer](#)

Transformer block



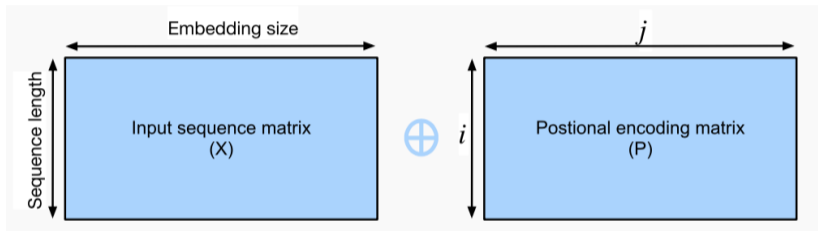
- Multi-head self-attention
 - Capture dependence among input symbols
- Positional encoding
 - Capture the order of symbols
- Residual connection and layer normalization
 - More efficient and stable optimization

Figure: From [The Illustrated Transformer](#)

Position embedding

Motivation: model word order in the input sequence

Solution: add a position embedding to each word



Position embedding:

- Encode absolute and relative positions of a word
- Same dimension as word embeddings
- Learned or deterministic

Sinusoidal position embedding

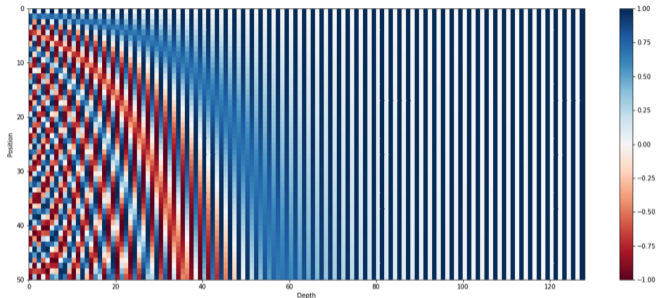
Intuition: continuous approximation of binary encoding of positions (integers)

0:	0	0	0	0
1:	0	0	0	1
2:	0	0	1	0
3:	0	0	1	1
4:	0	1	0	0
5:	0	1	0	1
6:	0	1	1	0
7:	0	1	1	1

Sinusoidal position embedding

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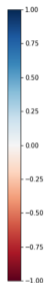
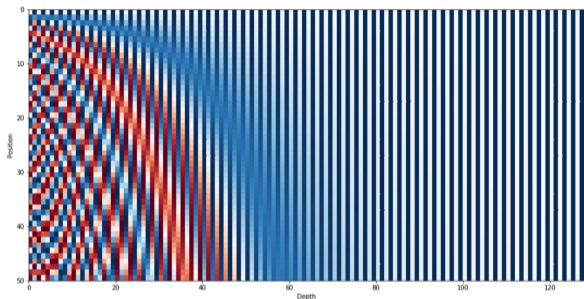
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$$\vec{p}_t = \begin{bmatrix} \sin(\omega_1 \cdot t) \\ \cos(\omega_1 \cdot t) \\ \\ \sin(\omega_2 \cdot t) \\ \cos(\omega_2 \cdot t) \\ \\ \vdots \\ \\ \sin(\omega_{d/2} \cdot t) \\ \cos(\omega_{d/2} \cdot t) \end{bmatrix}_{d \times 1}$$

Figure: From [Amirhossein Kazemnejad's Blog](#)

$$\omega_k = 1/10000 \frac{2k}{d}$$

Learned position embeddings

Sinusoidal position embedding:

- Not learnable
- Can extrapolate to longer sequences but doesn't work well

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Learned absolute position embeddings:

- Consider each position as a word. Map positions to dense vectors:
 $W_{d \times n} \phi_{\text{one-hot}}(\text{pos})$
- Column i of W is the embedding of position i

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Learned absolute position embeddings:

- Consider each position as a word. Map positions to dense vectors:
 $W_{d \times n} \phi_{\text{one-hot}}(\text{pos})$
- Column i of W is the embedding of position i
- Need to fix maximum position/length beforehand
- Cannot extrapolate to longer sequences

Residual connection

Motivation:

- Gradient explosion/vanishing is not RNN-specific!
- It happens to all very **deep** networks (which are **hard to optimize**).

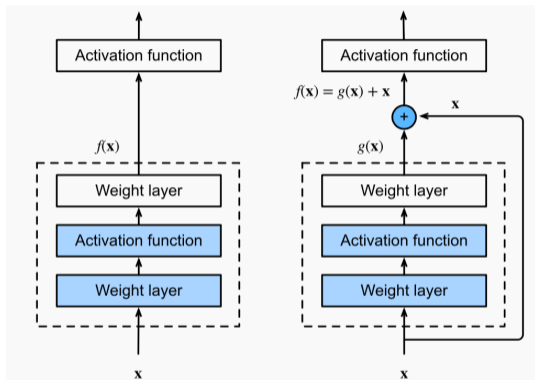
Residual connection

Motivation:

- Gradient explosion/vanishing is not RNN-specific!
- It happens to all very **deep** networks (which are **hard to optimize**).
- In principle, a deep network can always represent a shallow network (by setting higher layers to identity functions), thus it should be at least as good as the shallow network.
- For some reason, deep neural networks are bad at learning identity functions.
- How can we make it easier to recover the shallow solution?

Residual connection

Solution: [Deep Residual Learning for Image Recognition](#) [He et al., 2015]



Without residual connection: learn $f(x) = x$.

With residual connection: learn $g(x) = 0$ (easier).

Layer normalization

- **Problem:** inputs of a layer may shift during training
- **Solution:** normalize (zero mean, unit variance) across features [Ba et al., 2016]
- Let $x = (x_1, \dots, x_d)$ be the input vector (e.g., word embedding, previous layer output)

$$\text{LayerNorm}(x) = \frac{x - \hat{\mu}}{\hat{\sigma}},$$

$$\text{where } \hat{\mu} = \frac{1}{d} \sum_{i=1}^d x_i, \quad \hat{\sigma}^2 = \frac{1}{d} \sum_{i=1}^d (x_i - \hat{\mu})^2$$

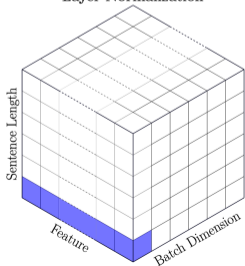
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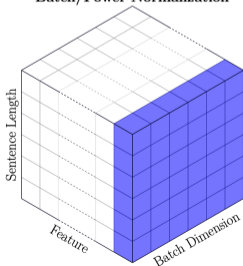
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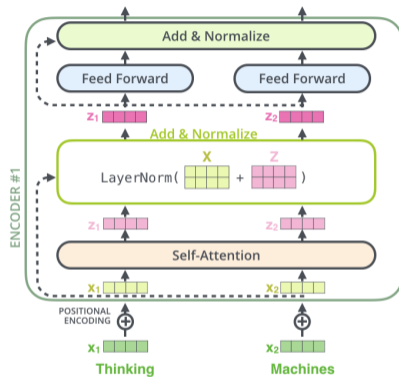


Batch/Power Normalization



- A deterministic transformation of the input
- Independent of train/inference and batch size

Residual connection and layer normalization in Transformer



- Add (residual connection) & Normalize (layer normalization) after each layer
- Position-wise feed-forward networks: same mapping for all positions

Summary

- We have seen two families of models for sequences modeling: **RNNs** and **Transformers**
- Both take a sequence of (discrete) symbols as input and output a sequence of embeddings
- They are often called **encoders** and are used to represent text
- Transformers are dominating today because of its scalability