# Pretraining and Finetuning (continued)

He He



October 16, 2024

# **Plan for today**

- Subword tokenization
- Efficient pre-training
- Parameter efficient finetuning

### <span id="page-2-0"></span>**Table of Contents**

[Tokenization](#page-2-0)

**Goal**: represent input string as a sequence of (meaningful) symbols

Approach so far: splitting string into "words"

**Goal**: represent input string as a sequence of (meaningful) symbols

Approach so far: splitting string into "words"

- What about words unseen in training?
	- Use UNK (limitations?)

**Goal**: represent input string as a sequence of (meaningful) symbols

Approach so far: splitting string into "words"

- What about words unseen in training?
	- Use UNK (limitations?)
	- We can guess word meaning based on its form, e.g., degrade  $\rightarrow$ degradation

**Goal**: represent input string as a sequence of (meaningful) symbols

Approach so far: splitting string into "words"

- What about words unseen in training?
	- Use UNK (limitations?)
	- We can guess word meaning based on its form, e.g., degrade  $\rightarrow$ degradation
- What about non-English languages? (Thai, Turkish, Chinese, Java, Lean etc.)
	- Take each character as a token (limitations?)

**Goal**: represent input string as a sequence of (meaningful) symbols

Approach so far: splitting string into "words"

- What about words unseen in training?
	- Use UNK (limitations?)
	- We can guess word meaning based on its form, e.g., degrade  $\rightarrow$ degradation
- What about non-English languages? (Thai, Turkish, Chinese, Java, Lean etc.)
	- Take each character as a token (limitations?)
	- Very long sequences; model needs to learn to compose characters

# **Subword tokenization: byte pair encoding**

What is a "token"?

- A sequence of characters that carries some meaning and *re-occurs* in a corpora
- Can we find these character units based on their *frequency*?

# **Subword tokenization: byte pair encoding**

What is a "token"?

- A sequence of characters that carries some meaning and *re-occurs* in a corpora
- Can we find these character units based on their *frequency*?

BPE tokenization: A middle ground between "words" and "characters"

- Origin: a compression algorithm that iteratively replace the most common character sequences by a single symbol
	- Output: compressed text + a look-up table
- Start with individual characters (or bytes) as tokens
- Count the frequency of every consecutive pair of tokens
- Merge the most frequent pair of tokens and treat them as a single token
- Update the text with the new token and repeat the process

### **BPE Example (Step-by-Step) Initial Sequence:**

- Words: banana, band, ban
- Initial tokenization:
	- b a n a n a
	- b a n d
	- b a n

### **BPE Example (Step-by-Step) Initial Sequence:**

- Words: banana, band, ban
- Initial tokenization:
	- b a n a n a
	- b a n d
	- b a n

#### **Step 1: Count Pairs**

• Most frequent pair: a n

### **BPE Example (Step-by-Step) Initial Sequence:**

- Words: banana , band , ban
- Initial tokenization:
	- b a n a n a
	- b a n d
	- b a n

#### **Step 1: Count Pairs**

• Most frequent pair: a n

#### **Step 2: Merge**

- New token: an
- Updated tokenization:
	- b an an a
	- b an d
	- b an

# **BPE Example (Step-by-Step)**

#### **Step 3: Count Pairs Again**

- Updated tokenization:
	- b an an a
	- b an d
	- b an
- Most frequent pair: b an

#### **Step 4: Merge**

- New token: ban
- Updated tokenization:
	- ban an a
	- ban d
	- ban

### <span id="page-14-0"></span>**BPE: practicalities**

- Repeat the process until the desired number of merges or vocabulary size is reached (a hyperparameter to decide).
- Typically vocabulary sizes are 32-64K
- Break ties deterministically, e.g., lexicographical order, occurrence in the corpus etc.
- Use bytes as the initial tokens (adopted by GPT-2)

### **Table of Contents**

[Efficient pretraining](#page-14-0)

### **Overview**

Approaches to speed up pretraining

### **Overview**

Approaches to speed up pretraining

- Reduce model size
- Design more sample-efficient learning objectives
- Improve efficiency of self-attention
- Improve system-level efficiency

# **Approach 1: Reduce model size**

Idea 1: reduce the number of parameters

ALBERT (a lite BERT) [\[Lan et al., 2020\]](https://arxiv.org/abs/1909.11942)

• **Factorization**:

- Recall that in Transformer, we first need to map the one-hot encoding (of size V) of a token to Q, K, V embeddings (of size  $H$ )
- The number of parameters is  $V \times H$
- We can instead first map it to a lower-dim space (of size  $E$ ) so that the number of params is  $V \times E + E \times H$

Idea 1: reduce the number of parameters

ALBERT (a lite BERT) [\[Lan et al., 2020\]](https://arxiv.org/abs/1909.11942)

#### • **Parameter sharing**:

- Share feedforward network weights across layers
- Share self-attention weights across layers
- ALBERT: share all params across layers

## **Approach 1: Reduce model size**

Idea 2: reduce interaction among parameters (sparse/modular architectures)

#### DEMix [\[Gururangan et al., 2022\]](https://aclanthology.org/2022.naacl-main.407.pdf)



- Replace the FFN layer with an ensemble of  $n$ experts
- Route examples to experts corresponding to its domain determinstically

$$
FFN(h) = \sum_{i=1}^{n} \mathbb{I}[x \in \text{domain } i] FFN_i(x)
$$

• Only a subset of params are active for each example/batch

# **Approach 1: Reduce model size**

Idea 2: reduce interaction among parameters (sparse/modular architectures)

Branch-Train-Merge [\[Li et al., 2022\]](https://arxiv.org/pdf/2208.03306.pdf)



- Train domain experts in parallel and ensemble them (or take weighted average of their parameters)
- Reduce synchronization among GPUs at the cost of increased model size
- Easy to expand/remove domain experts

# **Approach 2: design sample-efficient learning objectives**

ALBERT: Inter-sentence coherence loss

- Motivation: the next sentence prediction task is too easy
- Design hard negative examples
- Input: take two consecutive sentences, swap their order randomly
- Output: predict if they are in natural order *I went home.* SEP *I slept.* +1 *I slept.* SEP *I went home.* -1
- Model needs to learn temporal order of events (commonsense, causality etc.)

# **Approach 2: design sample-efficient learning objectives**

ELECTRA [\[Clark et al., 2020\]:](https://arxiv.org/abs/2003.10555) discriminate from true vs guessed tokens



- First train the generator for n steps using the MLM objective.
- Freeze generator weights. Train the discriminator using the sequence classification objective. Keep discriminator for finetuning.
- Comparison with MLM: predict at every position; hard negative examples.

# **Approach 2: design sample-efficient learning objectives** ELECTRA result:



#### Figure: Finetuning result on the GLUE benchmark

- Larger improvement at smaller model sizes
- Faster training
- An effective approach if you don't have large compute for pretraining

# **Approach 3: alternatives to self-attention**

Transformer recap



Figure: From [The Illustrated](https://jalammar.github.io/illustrated-transformer) [Transformer](https://jalammar.github.io/illustrated-transformer)

Which components require matrix multiplication?

# **Approach 3: alternatives to self-attention**

Transformer recap



Figure: From [The Illustrated](https://jalammar.github.io/illustrated-transformer) [Transformer](https://jalammar.github.io/illustrated-transformer)

Which components require matrix multiplication?

- Self-attention
	- Q,K,V projection
	- Scaled dot-product attention
- Feed-forward layer

Q, K, V projection:

$$
\boxed{n \times d_e} \quad \xrightarrow{\text{linear}} \quad n \times d
$$

Scaled dot-product attention:



Q, K, V projection:

$n \times d_e$	linear	$n \times d$	$O(n \times d_e \times d)$
----------------	--------	--------------	----------------------------

$$
O(n \times d_e \times d)
$$

Scaled dot-product attention:



Feed-forward layer (GPT-2):



 $O(n \times d \times d_h)$ 

- Two-layer FFN
- $d_h = 4d$  ( $d > 1K$ ) by default in GPT-2
- Approximately half of the compute time
- Concept check: how to reduce compute in FFN?

Feed-forward layer (GPT-2):



 $O(n \times d \times d_h)$ 

- Two-layer FFN
- $d_h = 4d$  ( $d > 1K$ ) by default in GPT-2
- Approximately half of the compute time
- Concept check: how to reduce compute in FFN?

### **Improve efficiency of self-attention (for long sequences)**

# **Improve efficiency of self-attention (for long sequences)**

**Key idea**: reduce the  $O(n^2)$  time and memory cost

- Sparsify the attention matrix
	- Deterministic mask
	- Data-dependent mask (Reformer [\[Kitaev et al., 2020\]\)](https://arxiv.org/pdf/2001.04451.pdf)
- Compress the key-value memory
	- Low-rank projection

### **Sparse attention**

#### **Longformer** [\[Beltagy et al., 2020\]:](https://arxiv.org/pdf/2004.05150.pdf) attention within a local window



- Sliding window: attending to a *local* window of size w around each token  $O(n \times w)$
- Dilated sliding window: reaching *longer range* with a larger window size with gaps
- Global window: *full attention* on specific tokens, e.g., [CLS] in BERT

### **Sparse attention**

#### **Longformer** [\[Beltagy et al., 2020\]:](https://arxiv.org/pdf/2004.05150.pdf) attention within a local window



- Sliding window: attending to a *local* window of size w around each token  $O(n \times w)$
- Dilated sliding window: reaching *longer range* with a larger window size with gaps
- Global window: *full attention* on specific tokens, e.g., [CLS] in BERT
- Details: balancing efficiency and performance
	- Adding dilation on some heads
	- Using small window size on lower layers and larger ones on higher layers

#### Self-attention is low rank [\[Wang et al., 2020\]](https://arxiv.org/pdf/2006.04768.pdf)



• Left: cumulative eigenvalues of pretrained transformer with  $n = 512$ 



- Left: cumulative eigenvalues of pretrained transformer with  $n = 512$ 
	- Most information in the attention matrix can be recovered by the top 128 eigenvectors



- Left: cumulative eigenvalues of pretrained transformer with  $n = 512$ 
	- Most information in the attention matrix can be recovered by the top 128 eigenvectors
- Right: cumulative eigenvalues of the top 128 eigenvalues across layers



- Left: cumulative eigenvalues of pretrained transformer with  $n = 512$ 
	- Most information in the attention matrix can be recovered by the top 128 eigenvectors
- Right: cumulative eigenvalues of the top 128 eigenvalues across layers
	- Higher layers are more low-rank



- Left: cumulative eigenvalues of pretrained transformer with  $n = 512$ 
	- Most information in the attention matrix can be recovered by the top 128 eigenvectors
- Right: cumulative eigenvalues of the top 128 eigenvalues across layers
	- Higher layers are more low-rank
- **Idea**: instead of attending to n tokens, attend to k principal components

**Linformer** [\[Wang et al., 2020\]:](https://arxiv.org/pdf/2006.04768.pdf) compute self-attention in a lower dimension



• Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$ 

**Linformer** [\[Wang et al., 2020\]:](https://arxiv.org/pdf/2006.04768.pdf) compute self-attention in a lower dimension



• Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$ 

• Attend to the lower-dimensional memory:  $\text{softmax}\left(\mathsf{Q}_{\bm{n}\times\bm{d}}\mathsf{K}_{\bm{k}\times\bm{d}}^{\bm{\mathcal{T}}}\right)$ √  $\overline{d}$ 



- Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$
- Attend to the lower-dimensional memory:  $\text{softmax}\left(\mathsf{Q}_{\bm{n}\times\bm{d}}\mathsf{K}_{\bm{k}\times\bm{d}}^{\bm{\mathcal{T}}}\right)$ √  $\overline{d}$ 
	- What's the dimension of the attention matrix?



- Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$
- Attend to the lower-dimensional memory:  $\text{softmax}\left(\mathsf{Q}_{\bm{n}\times\bm{d}}\mathsf{K}_{\bm{k}\times\bm{d}}^{\bm{\mathcal{T}}}\right)$ √  $\overline{d}$ 
	- What's the dimension of the attention matrix?
	- What's the dimension of the self-attention output?



- Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$
- Attend to the lower-dimensional memory:  $\text{softmax}\left(\mathsf{Q}_{\bm{n}\times\bm{d}}\mathsf{K}_{\bm{k}\times\bm{d}}^{\bm{\mathcal{T}}}\right)$ √  $\overline{d}$ 
	- What's the dimension of the attention matrix?
	- What's the dimension of the self-attention output?
- Computation cost:  $O(dnk)$  (linear in *n*)



- Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$
- Attend to the lower-dimensional memory:  $\text{softmax}\left(\mathsf{Q}_{\bm{n}\times\bm{d}}\mathsf{K}_{\bm{k}\times\bm{d}}^{\bm{\mathcal{T}}}\right)$ √  $\overline{d}$ 
	- What's the dimension of the attention matrix?
	- What's the dimension of the self-attention output?
- Computation cost:  $O(dnk)$  (linear in *n*)
- Downside of uisng Linformer as a decoder?



- Reduce dimensionality of the "memory": Map K, V from  $n \times d$  to  $k \times d$
- Attend to the lower-dimensional memory:  $\text{softmax}\left(\mathsf{Q}_{\bm{n}\times\bm{d}}\mathsf{K}_{\bm{k}\times\bm{d}}^{\bm{\mathcal{T}}}\right)$ √  $\overline{d}$ 
	- What's the dimension of the attention matrix?
	- What's the dimension of the self-attention output?
- Computation cost:  $O(dnk)$  (linear in *n*)
- Downside of uisng Linformer as a decoder?
	- Unclear how to mask: past and future are mixed

### **Summary on efficient self-attention**

Improve the quadratic time and space complexity of self-attention

- Sparsify the attention matrix
- Compress the KV memory

### **Summary on efficient self-attention**

Improve the quadratic time and space complexity of self-attention

- Sparsify the attention matrix
- Compress the KV memory

Bad news: Most techniques are not widely used in large pretrained models now. Why?

- Improvement in time/space complexity doesn't always translate to real time/space savings
- These techniques often breaks structure and sacrifice the batching ability on **GPUs**
- Only see improvement on very long sequences

# **Approach 4: system-level approaches**

- Operates at a lower abstraction level
- Often brings more direct impact on efficiency
- Example:
	- Gradient accumulation
	- Model and data parallelism (e.g., deepspeed)
	- Flash attention: exploit GPU memory asymmetry



### **Table of Contents**

[Efficient finetuning](#page-52-0)

# **Improve finetuning efficiency**

Problem:

- In NLP, typically all parameters of the pretrained models (e.g., BERT) are finetuned, which is expensive for large models.
- Saving and loading finetuned models for different tasks is costly.
- Potentially destroy pretrained representations

# <span id="page-52-0"></span>**Improve finetuning efficiency**

Problem:

- In NLP, typically all parameters of the pretrained models (e.g., BERT) are finetuned, which is expensive for large models.
- Saving and loading finetuned models for different tasks is costly.
- Potentially destroy pretrained representations

Can we finetune a smaller number of parameters to achieve performance similar to full finetuning?

# **Improve finetuning efficiency**

Problem:

- In NLP, typically all parameters of the pretrained models (e.g., BERT) are finetuned, which is expensive for large models.
- Saving and loading finetuned models for different tasks is costly.
- Potentially destroy pretrained representations

Can we finetune a smaller number of parameters to achieve performance similar to full finetuning?

- Select a subset of parameters from the pretrained weights to update
- Add a small number of parameters to adapte the (frozen) pretrained model

### **Finetune a subset of parameters**

Freezing the first X layers [\[Lee et al., 2019\]](https://arxiv.org/pdf/1911.03090.pdf)



A fourth of the layers need to be fine-tuned to obtain 90% of the performance.

### **Finetune a subset of parameters**

**BitFit** [\[Ben-Zaken et al., 2022\]:](https://arxiv.org/pdf/2106.10199.pdf) only finetune the bias term (0.1% of the parameters)

Amplifying / suppressing certain features?

Bias terms in QKV projection Bias terms in MLP layers

 $\mathbf{Q}^{m,\ell}(\mathbf{x}) = \mathbf{W}^{m,\ell}_{a} \mathbf{x} + \mathbf{b}^{m,\ell}_{a}$  $\mathbf{K}^{m,\ell}(\mathbf{x}) = \mathbf{W}^{m,\ell}_{k} \mathbf{x} + \mathbf{b}^{m,\ell}_{k}$  $\mathbf{V}^{m,\ell}(\mathbf{x}) = \mathbf{W}_v^{m,\ell} \mathbf{x} + \mathbf{b}_v^{m,\ell}$ 

$$
\begin{aligned} \mathbf{h}^{\ell}_2 &= \text{Dropout}\big(\mathbf{W}^{\ell}_{m_1}\cdot\mathbf{h}^{\ell}_1~+~\mathbf{b}^{\ell}_{m_1}\big)\\ \mathbf{h}^{\ell}_3 &= \mathbf{g}^{\ell}_{LN_1}\odot\frac{(\mathbf{h}^{\ell}_2+\mathbf{x})-\mu}{\sigma}+\mathbf{b}^{\ell}_{LN_1}\\ \mathbf{h}^{\ell}_4 &=~\text{GELU}\big(\mathbf{W}^{\ell}_{m_2}\cdot\mathbf{h}^{\ell}_3~+~\mathbf{b}^{\ell}_{m_2}\big)\\ \mathbf{h}^{\ell}_5 &= \text{Dropout}\big(\mathbf{W}^{\ell}_{m_3}\cdot\mathbf{h}^{\ell}_4~+~\mathbf{b}^{\ell}_{m_3}\big)\\ \text{out}^{\ell} &= \mathbf{g}^{\ell}_{LN_2}\odot\frac{(\mathbf{h}^{\ell}_5+\mathbf{h}^{\ell}_3)-\mu}{\sigma}+\mathbf{b}^{\ell}_{LN_2} \end{aligned}
$$

Result: 80.9 (BitFit, 0.08% params) vs 81.8 (full finetuning) on GLUE

#### **Adapter** [\[Houlsby et al., 2019\]:](https://arxiv.org/pdf/1902.00751.pdf) insert small networks to the pretrained model



- Insert learnable "adapters" in-between layers
- Adapters uses a bottleneck structure to reduce parameters
- Adapters uses a skip-connection

#### **Adapter** [\[Houlsby et al., 2019\]:](https://arxiv.org/pdf/1902.00751.pdf) insert small networks to the pretrained model



- Insert learnable "adapters" in-between layers
- Adapters uses a bottleneck structure to reduce parameters
- Adapters uses a skip-connection such that it can be "reduced" to the original frozen model

Result: less than 0.4% performance drop with 3% more parameters on GLUE

**LoRA** [\[Hu et al., 2021\]:](https://arxiv.org/pdf/2106.09685.pdf) add low-rank matrices as additional parameters



**Hypothesis**: weight matrices are low rank

Adapters: For any matrix multiplication  $h = W_0x$ , we modify it to

 $h = W_0x + \Delta Wx = W_0x + BAx$ 

• 
$$
W_0 \in \mathbb{R}^{d \times k}, B \in \mathbb{R}^{d \times r}, A \in \mathbb{R}^{r \times k} (r \ll k)
$$

- Initialization:  $BA = 0$
- Can be applied to any weight matrices, e.g., QKV projection matrices

Compare LoRA and the original adapters:

• LoRA recovers full finetuning by increasing r

Adapter recovers an MLP model with increasing params

Compare LoRA and the original adapters:

- LoRA recovers full finetuning by increasing r Adapter recovers an MLP model with increasing params
- LoRA has no additional inference cost

Compare LoRA and the original adapters:

• LoRA recovers full finetuning by increasing r

Adapter recovers an MLP model with increasing params

• LoRA has no additional inference cost by setting  $W_0 \leftarrow W_0 + BA$  (doesn't work for multiple tasks)

Adapter incurs additional inference cost due to the added params

The most widely used efficient finetuning method on very large models (>100B).

### **Summary**

Reduce finetuning cost by reducing the number of parameters to update

- Finetune a subset of parameters
- Finetune an additional adapters inserted to the model
- System approach: mixed-precision training (e.g., converting some or all params to fp16)

Other ways to adapt the model without parameter update: prompting, in-context learning (later)